## Curvature of Plane Curves

Suppose we have a curve à: IR-> IR, parametrized by arclength. Definition. If A: IR2->IR2 is the linear map "rotate by+172" given by  $A\vec{x} = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} X_1 \\ X_2 \end{bmatrix} = \begin{bmatrix} -X_2 \\ X_4 \end{bmatrix}$ , we let  $\vec{x} \stackrel{\perp}{=} A\vec{x}$ . Definition. The unit tangent vector  $T(s) = \dot{\alpha}'(s)$ . The unit normal vector N(s) = T(s)NG) NG) T(s)

Definition. The Gauss curvature of R(S) is defined by K\_(s) := < à"(s), N(s)) 111 - TIT ZANT negative zero conature positive Example. Circle of radius a, ccw parametrization.  $\overline{\alpha}(s) = (\alpha \cos(\frac{s}{a}), \alpha \sin(\frac{s}{a}))$  $\overline{\mathcal{X}}'(s) = (-\sin(\frac{s}{a}), \cos(\frac{s}{a})).$  $\widehat{\alpha}^{"}(s) = \left(-\frac{1}{a}\cos\left(\frac{s}{a}\right), -\frac{1}{a}\sin\left(\frac{s}{a}\right)\right).$  $T(s) = \overline{\alpha}'(s) = (-\sin(\frac{s}{a}), \cos(\frac{s}{a})).$  $N(s) = T(s)^{\perp} = (-\cos(\frac{s}{a}), -\sin(\frac{s}{a}))$  $K_{\pm}(s) = \langle \vec{\alpha}''(s), N(s) \rangle = \pm \frac{1}{\alpha} (s^{2} - s^{2} + \frac{1}{\alpha} s^{2} - s^{2} -$ 

Example. Circle of radius a, cw parametrization.  $\overline{\alpha}(s) = (\alpha \cos(-\frac{s}{a}), \alpha \sin(-\frac{s}{a}))$  $\vec{X}'(s) = (+sin(-\frac{s}{a}), -cos(-\frac{s}{a})).$  $\hat{\alpha}^{"}(s) = (-\frac{4}{a}\cos(-\frac{s}{a}), -\frac{4}{a}\sin(-\frac{s}{a})).$  $T(s) = \vec{\alpha}'(s) = (+sin(-\frac{s}{a}), -cos(-\frac{s}{a}))$  $N(s) = T(s)^{\perp} = (+cos(-\frac{s}{a}), + sin(-\frac{s}{a}))$  $K_{\pm}(s) = \langle \vec{\alpha}''(s), N(s) \rangle = -\frac{1}{a} \cos(-\frac{s}{a}) - \frac{1}{a} \sin^2(-\frac{s}{a})$ Proposition If  $\tilde{B}(s) = \tilde{\alpha}(-s), \chi_{\pm}^{B}(s) = -\chi_{\pm}^{\alpha}(s)$ Proof. We just compute:  $\vec{\beta}'(s) = -\vec{\alpha}'(-s), \quad \vec{\beta}''(s) = +\vec{\alpha}''(-s),$  $T^{\beta}(s) = -T^{\alpha}(s), N^{\beta}(s) = -N^{\alpha}(s),$  $\chi^{\beta}_{\pm}(s) = \langle \tilde{\beta}^{"}(s), N^{\beta}(s) \rangle$ = $\langle \tilde{\alpha}^{"}(s), -N^{\alpha}(s) \rangle = -K^{\alpha}_{\pm}(s).$ 团

Proposition If à(t) is a regular parametrization, then  $\chi_{\pm}(t) = \langle \vec{\alpha}''(t), \vec{\alpha}'(t)^{\perp} \rangle$  $\langle \vec{a}'(t), \vec{a}'(t) \rangle^{3/2}$ Proof. We know there exists some function t(s) so that alt(s)) is arclength parametrized. Further,  $t'(s) = \frac{1}{s'(t)} = \frac{1}{\|\vec{x}'(t)\|}$ Now  $\frac{d}{ds}\overline{\alpha}(t(s)) = \overline{\alpha}'(t(s)) \cdot t'(s) = T(t(s))$ SO N(t(s)) =  $T(t(s))^{\dagger} = \vec{\alpha}'(t(s))^{\dagger} \cdot t'(s)$ L is a linear map, so the scalar t's comes out  $\frac{d}{ds^{2}}\vec{\alpha}(t(s)) = \vec{\alpha}''(t(s)) \cdot t'(s)^{2} + \vec{\alpha}'(t(s)) \cdot t''(s)$ product role for scalar multiplication

Now that we're done differentiating, we'll stop writing "t(s)" and just write t.  $X_{\pm}(t) = \left\langle \frac{d^2}{ds^2} \vec{\chi}(t), N(t) \right\rangle$  $= \langle \vec{x}''(t) \cdot (t')^{2} + \vec{x}'(t) \cdot t', \vec{x}'(t) \cdot t' \rangle$ these are orthogonal!  $= \langle \vec{\alpha}^{(1)}(t), \vec{\alpha}^{(1)}(t)^{\perp} \rangle \cdot (t^{\prime})^{3}$  $t' = \frac{1}{\|\vec{\alpha}'(t)\|}$  $=\langle \vec{\alpha}''(t), \vec{\alpha}'(t)' \rangle$  $\langle \vec{x}'(t), \vec{x}'(t) \rangle^{3/2}$ 

Example. Ellipse  $\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$  $\vec{\alpha}(t) = (a \cos t, b \sin t)$  $\vec{\alpha}'(t) = (-\alpha \sin t, b \cos t)$  $\overline{\alpha}'(t) = (-b\cos t, -a\sin t)$  $\vec{\alpha}''(t) = (-\alpha \cos t, -b \sin t)$  $\chi_{\pm}(t) = \langle \vec{\alpha}''(t), \vec{\alpha}'(t) \rangle^{3/2} = \frac{ab}{(a^{2} \sin^{2} t + b^{2} \cos^{2} t)^{3/2}}$ 50  $K_{\pm}(0) = \chi_{\pm}(\pi) = \frac{ab}{b^3} = \frac{a}{b^2}$  $K_{\pm}(\pi_{2}) = X_{\pm}\left(\frac{3\pi}{2}\right) = \frac{ab}{a^{3}} = \frac{b}{a^{2}}$ Note: if b=a, this reduces to our previous calculation for circle.

Lemma. If  $\vec{v}(t)$ ,  $\vec{\omega}(t)$  are unit vectors in  $IR^2$  with  $\langle \vec{v}(t), \vec{\omega}(t) \rangle = 0$  for all t, くび、び〉= - くび、び〉 くジュンショー くば、ぶ入=0. Proof. All of these come from the product rule. (v(t), w(t))=0 for all t, so  $O = \frac{d}{dt} \langle \vec{v}(t), \vec{\omega}(t) \rangle$  $= \langle \vec{v}'(t), \vec{\omega}(t) \rangle + \langle \vec{v}(t), \vec{\omega}'(t) \rangle$ Further, because V(t) is a unit vector for all t,  $\langle \vec{v}(t), \vec{v}(t) \rangle = 1$  for all t,  $O = \frac{d}{dt} \langle \hat{v}(t), \hat{v}(t) \rangle$ = 2くない(+), む(+)> The proof that  $\langle \vec{\omega}, \vec{\omega} \rangle = 0$  is similar.

Definition. The orthogonal group  $O(n) = 2 A \in Mat_{n\times n} A^T = A^{-1} \xi$ and the special orthogonal group  $50(n) = \{A \in O(n) \mid det A = 1\}$ We think of O(n) as "orthonormal bases" and SO(n) as "positively oriented orthonormal bases" Proposition. If  $\hat{\alpha}(t)$  is a regular plane curve,  $F(t) = \begin{bmatrix} \hat{\tau}(t) & \hat{v}(t) \end{bmatrix} \in SO(2)$ . Proof. T(t) is a unit vector, so  $T(t) = (\cos \Theta(t), \sin \Theta(t))$  for some  $\Theta(t)$ .  $N(t) = T(t)^{\dagger} = (-\sin \Theta(t), \cos \Theta(t))$ . So  $F^{T}F = \begin{bmatrix} \leftarrow T(t) \rightarrow \\ \leftarrow N(t) \rightarrow \end{bmatrix} \begin{bmatrix} 1 \\ t \end{pmatrix} \begin{bmatrix} 1 \\ t \end{pmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$ and det  $F = \cos^2 \Theta(t) + \sin^2 \Theta(t) = 1$ .

Definition. If à(s) is an arclength parametrized curve in IR, we call the map F(s) = [T(s) N(s)] the Frenet Frame, and note F: IR-> SO(2). Proposition. In this case,  $X_{\pm}(s) N(s)$ T'(s) = $N'(s) = -\chi_{\pm}(s)T(s)$ (we call these the Frenet equations.) Proof. T. N is an orthonormal basis, so  $T' = \langle T', T \rangle T + \langle T', N \rangle N = K_{\pm} N$ = O (lemma) = K\_{1} (defn)  $N' = \langle N', T \rangle T + \langle N', N \rangle N = -X_{\pm} I.$ =- < N, T'> (lemma) =0 (lemma). - KI (defn)

Note that the Frenet equations imply  $F^{T}F' = \begin{bmatrix} \leftarrow T \rightarrow \\ \leftarrow N \rightarrow \end{bmatrix} \begin{bmatrix} T' & N' \\ \leftarrow & V \end{bmatrix} = \begin{bmatrix} O & -X_{\pm} \\ X_{\pm} & O \end{bmatrix}$ Proposition If F: IR->O(n), then F'=FS where S=-S (S is skew-symmetric) Proof. Set S=F<sup>T</sup>F! Then FS = FFF = F'L=I blc F is in So(n) Now FFF=I for all t so  $O = \frac{d}{dt} FF^{T} = F'F^{T} + F(F^{T})' = S + F(F^{T})'.$ Since FT has the same coordinate functions as F (just written in different places in the grid),  $(F^T)' = (F')'$  Thus  $F_{F}(F^{T})' = F_{F}(F^{T})^{T} = (F^{T}F^{T})^{T} = S^{T}$ We now have  $5+5^{T}=0$ . \//,

But what is Gauss curvature? N(s) (a(s) Assume Z(s) is parametrized by arclength, and consider N(s) sweeping back and forth around the unit circle, parametrized ccus by O.  $\frac{d\theta}{ds} = \langle N', N^{\perp} \rangle$  $=\langle \langle -\chi_{\pm}, T, (T^{\pm})^{\pm} \rangle$ Frenet equations defn  $= K_{\pm} \langle -T, -T \rangle$ R I rotates by TZ, so II rotates by T  $= X_{+}$ .

Definition. If à is a regular closed corve in IR<sup>2</sup> with length L, then we call SX+(s) ds the total curvature. Definition. A regular homotopy is a map  $\vec{\alpha}: S^1 \times [0, 1] \rightarrow \mathbb{R}^2$  so that for each fixed to, Z(s, to) is a regular parametrization of a cone in IR. We say à joins als, 0) and als, 1). ~(s,0)  $\vec{\alpha}(s,1)$ 

Theorem. If the and the are regular closed corves joined by a regular homotopy, they have the same total curvature. Proof. Since total convature doesn't Change under scaling or reparametrization, we may assume all à(s,t.) have length 21 and  $\vec{\alpha}: S^1 \times [0,1] \rightarrow \mathbb{R}^2$  has s as an arclength parameter on each curve. Consider and define a vector field  $\vec{\nabla} = (\langle N_s, N^{\perp} \rangle, \langle N_t, N^{\perp} \rangle)$ 

Now we recall Green's theorem, ) Vdlength = ) ] VxV dArea where if  $\vec{V} = (f, g), \nabla x \vec{V} = g_s - f_e$ . We compute  $\nabla x \overline{V} = \langle N_t, N^{\perp} \rangle_s - \langle N_s, N^{\perp} \rangle_t$ =  $\left\{ M_{\xi_{5}}, M^{\pm} \right\} + \left\langle N_{\xi_{5}}, N_{5}^{\pm} \right\rangle$ mixed partials commute -  $\left\{ M_{5\xi_{5}}, M^{\pm} \right\} - \left\langle N_{\xi_{5}}, N_{5}^{\pm} \right\rangle$ Now  $\langle N, N \rangle = 1$ , so  $\langle N_s, N \rangle = 0$  and  $\langle N_t, N \rangle = 0$ . But  $N, N^{\perp}$  are an orthonormal basis for IR', so this implies Ns and Nt are colinear - both are multiples of N-Thus  $\langle N_s, N_t^{\perp} \rangle = \langle N_t, N_s^{\perp} \rangle = 0$ .

By Green's theorem, we now have  $\int \vec{V} dlength$  $\bigcirc$  $= \int_{0}^{2\pi} \sqrt{(s,0)} (1,0) ds + \int_{0}^{1} \sqrt{(2\pi,t)} dt$  $-\int_{0}^{2\pi} \langle \vec{v}(s,1), (1,0) \rangle ds - \int_{0}^{1} \langle \vec{v}(0,1) \rangle dt$ the curves are closed, so V(0,t)=V(217,t)  $= \int_{0}^{2\pi} K_{\pm}^{0}(s) ds - \int_{0}^{2\pi} X_{\pm}(1) ds,$ which completes the proof!

If you took 3500/3510: For a single come, we have  $5^{1}$   $\ddot{N}$ 51 dO = length 1-form Total curvature = JN\*d0. For a homotopy between conves ST Ren N  $5^{1}$  x [0,1] 1] d0=length defn of boundary 1-form  $\int N^{*} d\Theta - \int N^{*} d\Theta = \int N^{*} d\Theta = \int d(N^{*} d\Theta)$   $S^{1} \times \{\Delta\} \qquad S^{1} \times \{O\} \qquad \partial(S^{1} \times \{O\}) \qquad S^{1} \times \{O\} = \int S^{1} \times \{O\} = \int N^{*} (d(\partial \Theta)) = \int N^{*} (d(\partial \Theta)) = \int N^{*} (\partial \Theta) = O$ 1 S1×[0,1]  $S^{\underline{1}} \times [0, \Delta]$ pullback and d commute

Whitney-Gravenstein Theorem. Every regular closed plane curve has total curvature 21TM, where nell and is regularly homotopic to 1) on n-covered circle, if n=0 2) the figure 8 conve, if n=0. Proof. Alas, beyond scope of this class! Example. HO  $\mathcal{C}$