

Transversality Theorem.

Suppose $F: X \times S \rightarrow Y$ is a smooth map of manifolds where only X has boundary and let $Z \subset Y$ be a submanifold without boundary.

If $F, \partial F$ transversal to Z , then for almost any $s \in S$, $f_s = F(-, s)$ and ∂f_s are transversal to Z .

~~"A small homotopy of any m"~~

Proof. We know

$W = F^{-1}(Z)$ is a mfld with boundary $W \cap \partial(X \times S)$.

Consider

$$\pi: X \times S \rightarrow S, \quad \pi(x, s) = s.$$

Claim. If s is a regular value of $\pi|_{\omega}$ and of $\partial\pi|_{2\omega}$, then $f_s \pitchfork Z$.

Take (x, s) so that $f_s(x) = z \in Z$. We must show that

$$d(f_s)_x T_{(x,s)}(X \times \{s\}) + T_z Z = T_z Y.$$

or, for any $\vec{a} \in T_z Y$, we must show $\exists \vec{v} \in d(f_s)_x T_{(x,s)}(X \times \{s\})$ so that

$$\vec{a} - d(f_s)_x(\vec{v}) \in T_z Z.$$

We know that for this \vec{a} , $\exists \vec{b} \in T_{(x,s)} X \times S$ so that

$$\vec{a} - dF_{(x,s)}(\vec{b}) \in T_z Z$$

(transversality of F w.r.t. Z). Now

$$T_{(x,s)} X \times S = T_x X \times T_s S$$

so our

$$\vec{b} = (\vec{\omega}, \vec{e}) \quad \text{for } \vec{\omega} \in T_x X, \vec{e} \in T_s S.$$

If $\vec{e} = 0$, then $\vec{\omega}$ would be our \vec{v} since

$$dF_{(x,s)}(\vec{\omega}, 0) = df_s(\vec{\omega}).$$

Plan: Modify \vec{b} to cancel \vec{e} .

We know that

$$d\pi_{(x,s)} : \begin{array}{c} T_{(x,s)}(X \times S) \\ \parallel \\ T_x X \times T_s S \end{array} \longrightarrow T_s S$$

is just the projection $(\vec{\omega}, \vec{e}) \rightarrow \vec{e}$. But $d\pi$ maps $T_{(x,s)}W$ onto $T_s S$ since s is a regular value of $\pi|_W$.

Thus $\exists (\vec{v}, \vec{e})$ so that $(\vec{v}, \vec{e}) \in T_{(x,s)}W$.

Observe that $F(\omega) \subset Z$, so

$$dF_{(x,s)}(\vec{v}, \vec{e}) \in T_z Z.$$

We claim

$$\vec{v} = \vec{\omega} - \vec{u}$$

has the property that

$$a - df_s(\vec{v}) \in T_z Z.$$

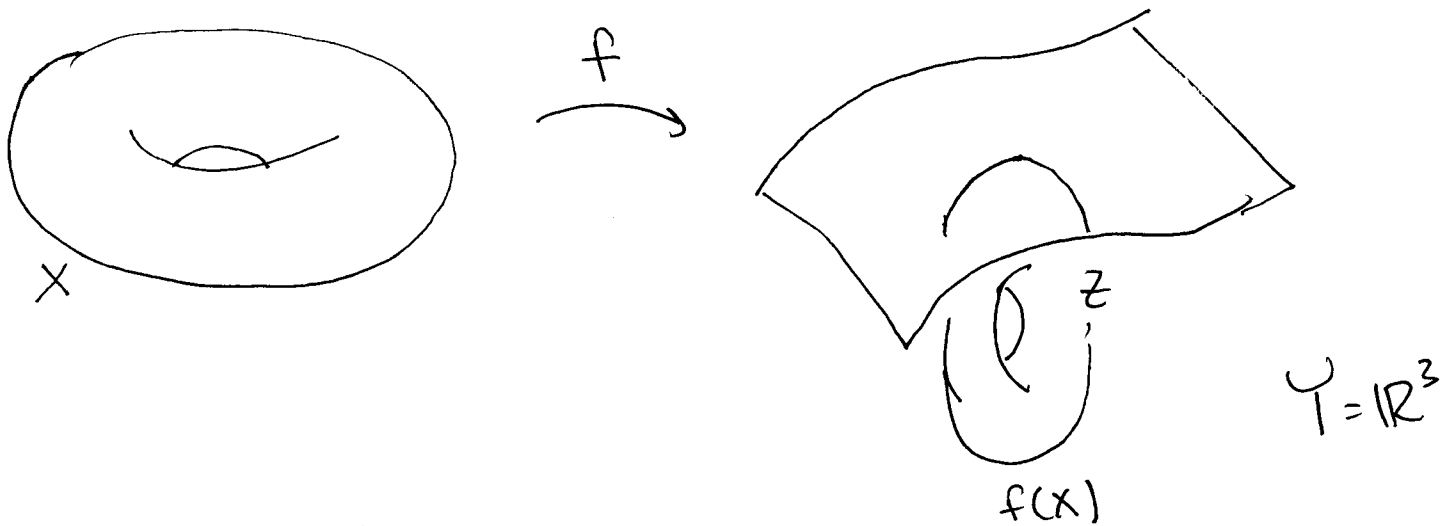
We check

$$\begin{aligned} a - df_s(\vec{v}) &= a - dF_{(x,s)}(\vec{v}, 0) \\ &= a - dF_{(x,s)}(\vec{\omega} - \vec{u}, \vec{e} - \vec{e}) \\ &= a - \left[dF_{(x,s)}(\vec{\omega}, \vec{e}) \right] + dF_{(x,s)}(\vec{v}, \vec{e}) \\ &= \underbrace{a - dF_{(x,s)}(\vec{b})}_{\text{in } T_z Z \text{ by construction of } \vec{b}} + \underbrace{dF_{(x,s)}(\vec{v}, \vec{e})}_{\text{in } T_z Z \text{ by construction of } (\vec{v}, \vec{e})} \\ &\in T_z Z. \end{aligned}$$

⑤

Since Sard's theorem says almost every $s \in S$ is a regular value, we're done.

Now imagine



If we build

$$F: X \times \mathbb{R}^3 \rightarrow Y \quad \text{by} \quad F(x, \vec{s}) = f(x) + \vec{s}$$

then F is a submersion onto Y so F is always transverse to any $Z \subset Y$.

⑥
By the Theorem above, almost every variation $\xi \in \mathbb{R}^3$ makes the map $f(x) + s$ transverse to Z .

Idea: Transverse maps are the only observable maps.

What if Y is not Euclidean space?

We need to pretend it is...

ϵ -Neighborhood theorem.