

Intersection # for submanifolds

(1)

We have defined

$I(f, Z)$ and proved that it is a homotopy invariant of f . But this is somewhat unsatisfying... what if Z were to change by homotopy?

We want to define

$I(X, Z)$

when X, Z are compact, boundaryless submanifolds of Y with complementary dimension (and everything is oriented).

Definition. $f \# g \Leftrightarrow df_x(T_x X) + dg_z(T_z Z) = T_y Y$
when $f: X \rightarrow Y, g: Z \rightarrow Y$ take $x \mapsto y, z \mapsto y$.

Definition. The local intersection # of f, g at $\text{soc}(x, z)$ is $+1$ if the orientations on

(2)

$$df_*(T_x X) \text{ and } dg_*(T_z Z)$$

add up (in that order) to the orientation
on $T_y Y$, and -1 otherwise.

We then have

Definition. $I(f, g) = \sum_{(x,z) \rightarrow y} \text{local intersection \# at } (x,z).$

We need to show that $I(f, g)$ is finite.

Idea: Consider

$$f \times g : X \times Z \rightarrow Y \times Y.$$

when $f(x) = g(z)$, then $(f \times g)(x, z)$ intersects
the diagonal of $Y \times Y$. So we want to
show that

$$I(f \times g, \Delta) = I(f, g)$$

This is almost true, but a sign gets in
the way.

(3)

Lemma. Let U, W be subspaces of V .

Then

$$U \oplus W = V \iff U \times W \oplus \Delta = V \times V$$

If U, W are oriented, and V has the sum ~~product~~ orientation, let Δ have the orientation induced from V by the isomorphism $V \rightarrow \Delta$.

The product orientation on $V \times V$ agrees with the sum orientation from $U \times W \oplus \Delta$
 $\iff W$ is even dimensional.

In our case, this implies

Proposition. $f \pitchfork g \iff f \times g \pitchfork \Delta$ and

$$I(f, g) = (-1)^{\dim Z} I(f \times g, \Delta).$$

(4).

While $I(f,g)$ is only defined if $f \neq g$, $I(f \times g, \Delta)$ is always defined, so we can use this to extend the def. of $I(f,g)$.

Consequences.

If $f_0 \simeq f_1$, $g_0 \simeq g_1$, then $I(f_0, g_0) = I(f_1, g_1)$.

If Z is a submanifold of Y and $i: Z \rightarrow Y$ the inclusion, then $I(f, i) = I(f, Z)$, for any map f .

$\deg(f)$ is well-defined.