

The Variational Approach and Elliptic PDE ①

We want to show that harmonic functions obey a really amazing property:

$$\Delta u = 0 \text{ on } \Omega \\ \text{with } u = f \text{ on } \partial\Omega$$

\Leftrightarrow u is the minimizer of the functional $D(v, v) = \int_{\Omega} \nabla v \cdot \nabla v \, dV$ among functions with $u = f$ on $\partial\Omega$.

This will lead us to some new numerical methods for the Laplace, and in general for elliptic PDE problems.

(2)

Green's Identity 1. For functions u and v on a domain Ω with smooth boundary S

$$\int_S (v \nabla u) \cdot \vec{n} \, d\text{Area} = \int_{\Omega} v \Delta u + \nabla u \cdot \nabla v \, d\text{Vol}.$$

We compute

$$\begin{aligned} \nabla \cdot (v \nabla u) &= \sum_i \frac{\partial}{\partial x_i} (v \nabla u)_i \\ &= \sum_i \frac{\partial}{\partial x_i} v \frac{\partial u}{\partial x_i} \\ &= \sum_i \left(\frac{\partial v}{\partial x_i} \right) \cdot \left(\frac{\partial u}{\partial x_i} \right) + v \frac{\partial^2 u}{\partial x_i^2} \\ &= \nabla v \cdot \nabla u + v \Delta u. \end{aligned}$$

Now this is just the divergence theorem.

Green's Identity 2. If Ω is a domain with smooth boundary S , then

③

$$\int_S v(\nabla u \cdot \vec{n}) - u(\nabla v \cdot \vec{n}) dArea = \\ = \int_{\Omega} (v \Delta u - u \Delta v) dVol$$

(Just switch u and v in identity 1 and subtract.)

Now suppose u, v both equal f on $\partial\Omega$, $\Delta u = 0$.
 We have

$$D(u-v, u+v) = \int_{\Omega} (\nabla u - \nabla v) \cdot (\nabla u + \nabla v) dVol$$

$$= D(u, u) - D(v, v)$$

But \neq

$$\int_{\Omega} \nabla(u-v) \cdot \nabla(u+v) dVol = \leftarrow \text{Green's Id 1.}$$

$$\int_{\Omega} (u-v) \nabla(u+v) \cdot \vec{n} dArea$$

$$- \int_{\Omega} (u-v) \Delta(u+v) dVol$$

$$= \int_{\Omega} (u-v) \Delta v dVol \quad \leftarrow \text{since } \Delta u = 0$$

$$= \int_{\Omega} (u-v) \Delta(u-v) dVol$$

$$= - \int_{\Omega} \nabla(u-v) \cdot \nabla(u-v) dVol + \int_{\partial\Omega} (u-v) \nabla(u-v) \cdot \vec{n} dA$$

$$\leq 0.$$

This proves that for any v on Ω obeying the same boundary conditions,

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$$D(u, u) \leq D(v, v)$$

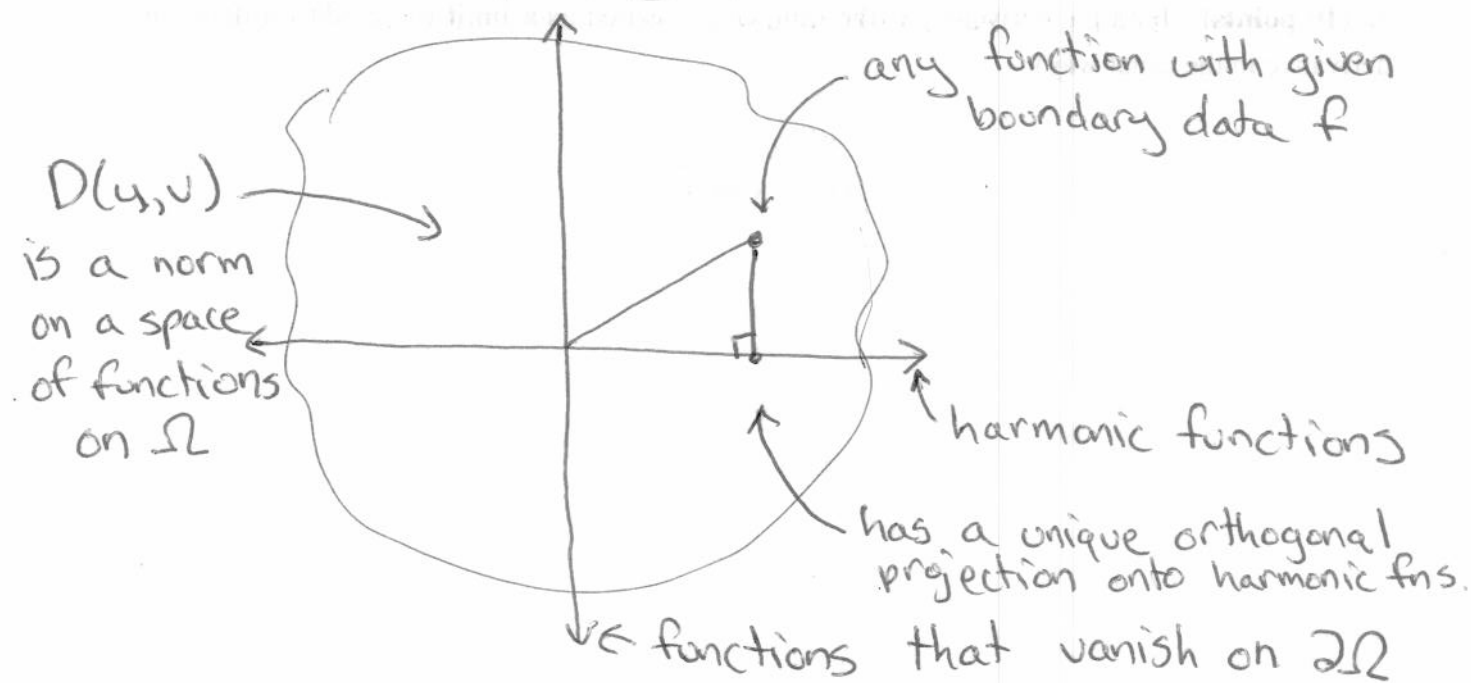
if $\Delta u = 0$ on Ω .

Remarks.

- 1) This does not prove that such a u exists, but we could do this properly (eg 2F of Folland) and prove that as well.
- 2) We can use this to obtain specific solutions in many cases.

3) There's a pretty picture here:

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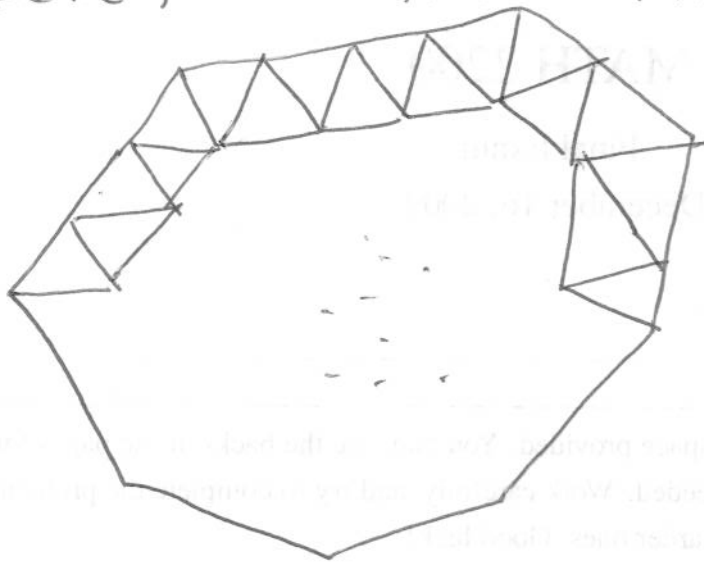


4) Actually, we could do this for a general elliptic problem (but the details of D would change, cf chapter 7 of Folland).

5) We need one more case:

$$\Delta u = r \quad \Leftrightarrow \quad u \text{ minimizes}$$
$$D(u, u) = \int_{\Omega} \nabla u \cdot \nabla u + 2ru \, d\Omega$$

A (better) method of finite elements. (1)



We now use this observation to build a better solver.

Idea: Suppose we triangulate Ω and allow values at mesh points to vary, assuming u is piecewise linear on triangles. We could take



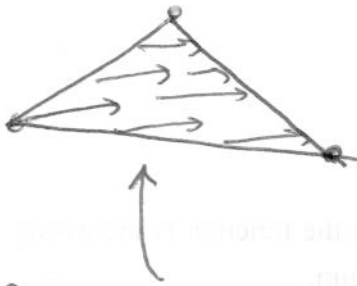
mesh point
 (x_i, y_i, z_i)

↔ now try to write down Δu for vertex in terms of mesh vals.

(old approach)

(new idea)

8



if u is linear
on this triangle
 ∇u is constant



write down:

$$\int_{\Delta_i} \nabla u \cdot \nabla u \, dVol$$

Δ_i
as a linear function
of the ~~are~~ vertices
of the triangle
and minimize the
function

$$\sum_i \int_{\Delta_i} \nabla u \cdot \nabla u \, dVol$$

This is (a) finite element method and
we will see it's pretty powerful.