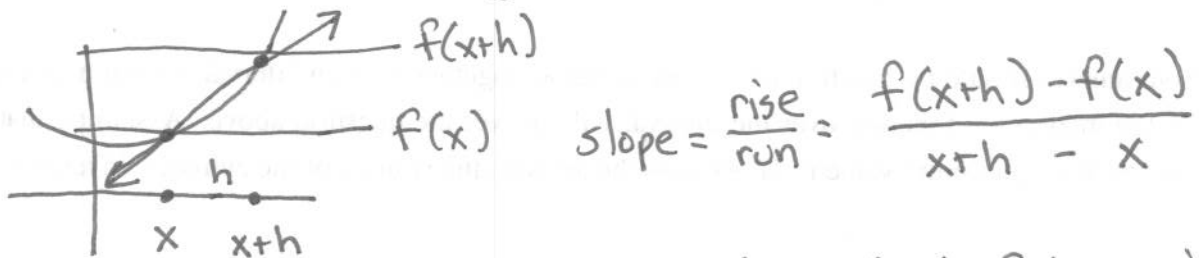


Robot Calculus - Lecture 1. (31, WWT)

Let $f(x)$ be a function. Our big idea is to measure the change in f as x changes.



Example. $f(t)$ = miles from Atlanta. t = # of hours since start
 At noon, you start in Atlanta $f(0) = 0$. At 1 pm, you arrive in Athens, $f(1) = 75$.

Average rate of change vs. speedometer (instant. rate of change)

Definition. The derivative $f'(x) = \lim_{h \rightarrow 0} \frac{f(x+h) - f(x)}{h}$.

Limits work just as you hope except

$\lim_{x \rightarrow a} \frac{f(x)}{g(x)}$ is unknown if $\lim_{x \rightarrow a} g(x) = 0$.

Basically every function in this class is continuous, which means $\lim_{x \rightarrow a} f(x) = f(a)$, ~~as long~~ when $f(a)$ exists.

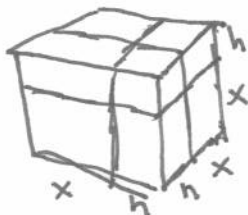
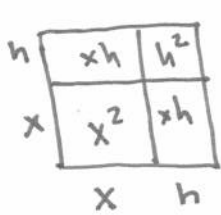
position $\xrightarrow{d/dt}$ velocity $\xrightarrow{d/dt}$ acceleration

~~finding the~~

Robot Calculus - Lecture 2. (3.2, HWT)

Consider $f(x) = x$. $\frac{d}{dx} f(x) = \lim_{h \rightarrow 0} \frac{(x+h) - x}{(x+h) - x} = \lim_{h \rightarrow 0} 1 = 1$.

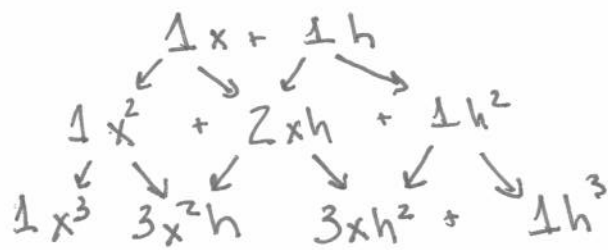
Now do $f(x) = x^2$. $\frac{d}{dx} f(x) = 2x$.



$$= x^3 + 3x^2h + 3xh^2 + h^3$$

$$\begin{aligned} (x^3 + 3x^2h + 3xh^2 + h^3)(x+h) &= x^4 + 3x^3h + 3x^2h^2 + xh^3 + \\ &\quad x^3h + 3x^2h^2 + 3xh^3 + h^4 \\ &= x^4 + 4x^3h + 6x^2h^2 + 4xh^3 + h^4 \end{aligned}$$

We can turn this into a game!



= Pascal's triangle.



So $(x+h)^{17} = x^{17} + 17x^{16}h + \dots + x^{15}h^2 + \dots + h^{17}$,

and

$$\begin{aligned} \frac{d}{dx} x^{17} &= \lim_{h \rightarrow 0} \frac{(x+h)^{17} - x^{17}}{h} = \lim_{h \rightarrow 0} \frac{17x^{16}h + \dots + h^{17}}{h} \\ &= \lim_{h \rightarrow 0} 17x^{16} + \dots + h^{16} = 17x^{16} \end{aligned}$$

Rule: $\frac{d}{dx} x^n = n x^{n-1}$. Sum rule, constant rule, derivative of constant fn = 0.

Robot Calculus - Lecture 3. (3.3, HWT)

Newton's laws. $f = ma$. force of gravity = $\frac{m_1 m_2}{d^2} \approx \downarrow gm_1$ ^{constant}

So a thrown object near earth obeys

$$gm = ma, \quad a = g \approx -9.8 \text{ m/s}^2 \text{ or } -32 \text{ ft/sec}^2$$

regardless of mass, in the y-direction, and $0 = ma \Rightarrow a = 0$ in the x-direction (no force, no acceleration!).

position $p(t) \xrightarrow{d/dt}$ velocity $v(t) \xrightarrow{d/dt}$ acceleration $a(t)$

If

$$p(t) = \frac{A}{2}t^2 + Bt + C, \quad v(t) = At + B, \quad a(t) = A.$$

So for vertical motion, $p(t) = y(t)$, $a_y(t) = g$,

$$v_y(t) = gt + v_0 \leftarrow \text{velocity at time } 0$$

$$y(t) = \frac{g}{2}t^2 + v_0 t + y_0 \leftarrow \text{position at time } 0$$

For horizontal motion, $a_x(t) = 0$, so we have

$$v_x(t) = v_0, \quad x(t) = v_0 t + x_0 \leftarrow \text{position at time } 0.$$

Example. At time 0, a tennis ball is thrown with an x-velocity of 2 m/s and a y-velocity of 4 m/s from the point (0, 2). What path does it follow? Where does it land?

Lab. Fitting, predicting, and intercepting!

Robot Calculus - Lecture 4 (3.2 HWT)

$$\begin{aligned} \frac{d}{dx} f(x)g(x) &= \lim_{h \rightarrow 0} \frac{f(x+h)g(x+h) - f(x)g(x)}{h} \\ &= \lim_{h \rightarrow 0} \frac{f(x+h)g(x+h) - f(x+h)g(x) + f(x+h)g(x) - f(x)g(x)}{h} \\ &= \lim_{h \rightarrow 0} f(x+h) \left[\frac{g(x+h) - g(x)}{h} \right] + \lim_{h \rightarrow 0} g(x) \left[\frac{f(x+h) - f(x)}{h} \right] \\ &= f(x)g'(x) + f'(x)g(x). \quad (\text{product rule}). \end{aligned}$$

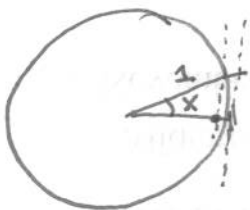
Example. $(x^2 + 3x^5 + x + 7)(x^6 + 3x - 6)$

$$\begin{aligned} \frac{d}{dx} \frac{f(x)}{g(x)} &= \lim_{h \rightarrow 0} \frac{\frac{f(x+h) - f(x)}{g(x+h)g(x)}}{h} = \lim_{h \rightarrow 0} \frac{f(x+h)g(x) - f(x)g(x+h)}{h g(x)g(x+h)} \\ &= \lim_{h \rightarrow 0} \frac{f(x+h)g(x) - f(x)g(x) + f(x)g(x) - f(x)g(x+h)}{h g(x)g(x+h)} \\ &= \lim_{h \rightarrow 0} \frac{g(x) \lim_{h \rightarrow 0} \frac{f(x+h) - f(x)}{h} - f(x) \lim_{h \rightarrow 0} \frac{g(x+h) - g(x)}{h}}{g(x)g(x+h)} \\ &= \frac{f'(x)g(x) - f(x)g'(x)}{g^2(x)} \quad (\text{quotient rule}) \end{aligned}$$

Example. $\frac{x^2 + 3}{x - 7}$

In-class creativity exercise. $1 = \sin^2 \theta + \cos^2 \theta = \dots$
(Find as many equivalent forms as you can in 5 minutes).

Limit of $\sin x/x$.



$$\begin{aligned} \text{Area of inner triangle} &= \frac{1}{2} \sin \theta \cos \theta \\ \text{Area of sector} &= \pi \cdot \frac{\theta}{2\pi} = \frac{1}{2} \theta \\ \text{Area of outer triangle} &= \frac{1}{2} \cdot 1 \cdot \tan \theta \\ &\Downarrow \\ \frac{1}{2} \sin \theta \cos \theta &< \frac{1}{2} \theta < \frac{1}{2} \frac{\sin \theta}{\cos \theta} \\ &\Downarrow \\ \cos \theta &< \frac{\theta}{\sin \theta} < \frac{1}{\cos \theta} \Rightarrow \lim_{\theta \rightarrow 0} \frac{\theta}{\sin \theta} = 1. \end{aligned}$$

Robot Calculus - Lecture 5 (3.4 HWT)

$$\frac{d}{dx} \sin(x) = \lim_{h \rightarrow 0} \frac{\sin(x+h) - \sin x}{h} = \lim_{h \rightarrow 0} \frac{\sin x \cos h + \cos x \sin h - \sin x}{h}$$

$$= \lim_{h \rightarrow 0} (\sin x) \left(\frac{\cos h - 1}{h} \right) + \lim_{h \rightarrow 0} \cos x \frac{\sin h}{h}$$

$$= \sin x \lim_{h \rightarrow 0} \frac{\cos h - 1}{h} \cdot \frac{\cos h + 1}{\cos h + 1} + \cos x$$

$$= \sin x \lim_{h \rightarrow 0} \frac{\cos^2 h - 1}{h(\cos h + 1)} + \cos x = \sin x \lim_{h \rightarrow 0} \frac{-\sin^2 h}{h(\cos h + 1)} + \cos x$$

$$= \cos x.$$

$$\frac{d}{dx} \cos x = \lim_{h \rightarrow 0} \frac{\cos(x+h) - \cos x}{h} = \lim_{h \rightarrow 0} \frac{\cos x \cos h - \sin x \sin h - \cos x}{h}$$

$$= -\sin x \cdot \lim_{h \rightarrow 0} \frac{\sin h}{h} + \cos x \lim_{h \rightarrow 0} \frac{\cos h - 1}{h} = -\sin x.$$

$$\frac{d}{dx} \tan x = \frac{d}{dx} \frac{\sin x}{\cos x} = (\text{quotient rule}) = \frac{1}{\cos^2 x} = \sec^2 x.$$

Circular motion. A fan blade spins at 500 rpm. What are the vertical and horizontal position, velocity, and acceleration of a point 1 ft from the center? As a fn of θ ? At $\theta = \pi/3$?

Parametrizing the circle by $(r \cos \frac{\theta}{K}, r \sin \frac{\theta}{K})$. How to determine r and K .

Other trig derivatives.

Robot Calculus - Lecture 6.

Rates of change as we change the units of time,
and as we multiply t by k . $\frac{d}{dt} f(kt) = kf'(kt)$.

Chain Rule. $\frac{d}{dx} f(g(x)) = f'(g(x))g'(x)$.

what it means to compose functions. $x \rightarrow \boxed{f} \xrightarrow{f(x)} \boxed{g} \xrightarrow{g(f(x))} \dots$

Algebra of composition, (examples).

Creativity exercise. Write $\sin(x^2+1) + (x^2+1)^4$ as a composition
in as many ways as you can in 5 minutes.

→ and chain rule examples.

Circular motion examples for $(r \cos \theta/k, r \sin \theta/k)$.

Target Tracking Lab!!!

Robot Calculus - Lecture 6

Rates of change and changing units of time. $\frac{d}{dt} f(kt)$.

Composition of functions $x \rightarrow \boxed{g} \xrightarrow{g(x)} \boxed{f} \xrightarrow{f(g(x))}$

algebra of compositions. examples.

Creativity exercise. Write $\sin(x^2+1) + (x^2+1)^4$ as a composition in as many ways as you can.

Chain Rule. $\frac{d}{dx} f(g(x)) = f'(g(x)) \cdot g'(x)$.

Examples. Derivatives of $(r \cos \theta/k, r \sin \theta/k)$.

Lab: Trajectory of stuff launched from a wheel.

Robot Calculus - Lecture 7. (3.3 HWT)

What about $f(x) = a^x$?

$$\frac{d}{dx} a^x = \lim_{h \rightarrow 0} \frac{a^{x+h} - a^x}{h} = \lim_{h \rightarrow 0} \frac{a^x a^h - a^x}{h} = a^x \cdot \left(\lim_{h \rightarrow 0} \frac{a^h - 1}{h} \right)$$

where $\lim_{h \rightarrow 0} \frac{a^h - 1}{h} = g(a)$ for some function g . So we have

$$\frac{d}{dx} a^x = a^x g(a).$$

That's weird. What's $g(a)$? Calculator experiments.

Definition. e is the number for which $g(e) = 1$, or $\frac{d}{dx} e^x = e^x$.
 $e \approx 2.718281828\dots$

Recall that $\log_a x =$ the power y so that $a^y = x$.

Example. $\log_{10} x =$ # of digits in x . $\log_e e^x = x$

$$\frac{d}{dx} e^{\ln x} = e^{\ln x} \cdot \frac{d}{dx} \ln x = x \cdot \frac{d}{dx} \ln x.$$

$$\frac{d}{dx} x = 1. \quad \text{So } x \cdot \frac{d}{dx} \ln x = 1 \text{ and } \frac{d}{dx} \ln x = \frac{1}{x}.$$

Examples for $\ln x$ and e^x derivatives.

Challenge problem. Derivative of x^x . Rewrite as many ways as you can. What about $(x^x)^x$?