New algorithms for sampling closed and/or confined equilateral polygons

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Definition

A random (open) polygon in \mathbb{R}^3 is a set of edge vectors $\vec{e}_1, \ldots, \vec{e}_n$ sampled independently from the unit sphere. We call this sample space

$$\operatorname{Arm}(n) := \underbrace{S^2 \times \cdots \times S^2}_{n \text{ times}}$$

Definition

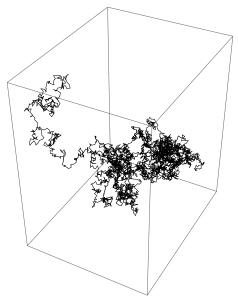
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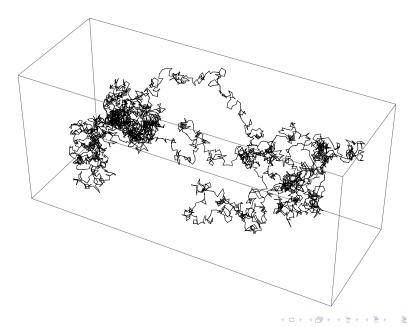
A random closed polygon conditions these samples on the hypothesis that $\sum \vec{e}_i = \vec{0}$, or samples from the submanifold of Arm(*n*) where $\sum \vec{e}_i = 0$, which we denote Pol(*n*).

Open Equilateral Random Polygon with 3,500 edges



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- What is the joint pdf of edge vectors in a closed walk?
- What can we prove about closed random walks?
 - What is the marginal distribution of a single chord length?
 - What is the joint distribution of several chord lengths?
 - · What is the expectation of radius of gyration?
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 - What if the walk is confined to a sphere? (Confined DNA)
 - What if the edge lengths vary? (Loop closures)
 - Can we get error bars?

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Point of Talk

New sampling algorithms backed by deep and robust mathematical framework. Guaranteed to converge. Hard math, relatively easy code.

(Incomplete?) History of Sampling Algorithms

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- Markov Chain Algorithms
 - crankshaft (Vologoskii 1979, Klenin 1988)
 - polygonal fold (Millett 1994)
- Direct Sampling Algorithms
 - triangle method (Moore 2004)
 - generalized hedgehog method (Varela 2009)
 - sinc integral method (Moore 2005, Diao 2011)

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- Direct Sampling Algorithms
 - triangle method (Moore et al. 2004)
 - samples a subset of closed polygons
 - generalized hedgehog method (Varela et al. 2009)
 - unproved whether this is correct pdf
 - sinc integral method (Moore et al. 2005, Diao et al. 2011)
 - requires sampling from complicated 1-d polynomial PDFs

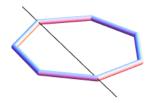
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Definition

A *fold move* or *bending flow* rotates an arc of the polygon around the axis its endpoints.

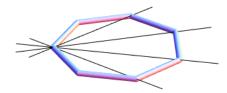
The polygonal fold Markov chain selects arcs and angles at random and folds repeatedly.



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Definition

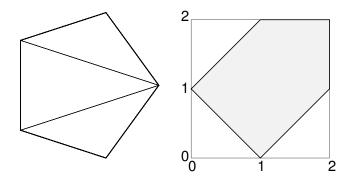
Given an (abstract) triangulation of the *n*-gon, the folds on any two chords commute. A *dihedral angle* move rotates around all of these chords by independently selected angles.



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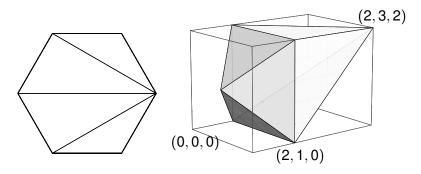
Definition

A abstract triangulation *T* of the *n*-gon picks out n-3 nonintersecting chords. The lengths of these chords obey triangle inequalities, so they lie in a convex polytope in \mathbb{R}^{n-3} called the *triangulation polytope* \mathcal{P} .



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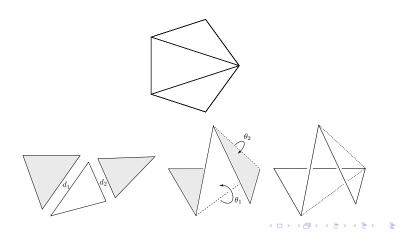


Action-Angle Coordinates

Definition

If \mathcal{P} is the triangulation polytope and T^{n-3} is the torus of n-3 dihedral angles, then there are *action-angle coordinates*:

$$\alpha: \mathcal{P} \times T^{n-3} \to \operatorname{Pol}(n) / \operatorname{SO}(3)$$



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Theorem (with Shonkwiler)

 α pushes the **standard probability measure** on $\mathcal{P} \times T^{n-3}$ forward to the **correct probability measure** on Pol(*n*)/SO(3).

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Theorem (with Shonkwiler)

 α pushes the **standard probability measure** on $\mathcal{P} \times T^{n-3}$ forward to the **correct probability measure** on Pol(*n*)/SO(3).

Proof.

Millson-Kapovich toric symplectic structure on polygon space + Duistermaat-Heckmann theorem + Hitchin's theorem on compatibility of Riemannian and symplectic volume on symplectic reductions of Kähler manifolds + Howard-Manon-Millson analysis of polygon space.

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Corollary

Any sampling algorithm for convex polytopes is a sampling algorithm for closed equilateral polygons.

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Proposition (with Shonkwiler)

The joint pdf of the n - 3 chord lengths in an abstract triangulation of the n-gon in a closed random equilateral polygon is Lesbegue measure on the triangulation polytope.

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Proposition (with Shonkwiler)

The joint pdf of the n - 3 chord lengths in an abstract triangulation of the n-gon in a closed random equilateral polygon is Lesbegue measure on the triangulation polytope. The marginal pdf of a single chordlength is a piecewise-polynomial function given by the volume of a slice of the triangulation polytope in a coordinate direction.

These marginals derived by Moore/Grosberg 2004 and Diao/Ernst/Montemayor/Ziegler 2011.

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Corollary (with Shonkwiler)

The expectation of any function of a collection of non-intersecting chordlengths can be computed by integrating over the triangulation polytope.

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Proposition (with Shonkwiler)

The expected length of a chord skipping k edges in an n-gon is the k - 1 st coordinate of the center of mass of the fan triangulation polytope.

We can check these centers of mass against the first moments of the MG-DEMZ chordlength marginals:

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n	<i>k</i> = 2	3	4	5	6	7	8
4	1						
5	<u>17</u> 15	<u>17</u> 15					
6	<u>14</u> 12	<u>15</u> 12	<u>14</u> 12				
7	<u>461</u> 385	<u>506</u> 385	<u>506</u> 385	<u>461</u> 385			
8	<u>1,168</u> 960	<u>1,307</u> 960	<u>1,344</u> 960	<u>1,307</u> 960	<u>1,168</u> 960		
9	<u>112,121</u> 91,035	<u>127,059</u> 91,035	<u>133,337</u> 91,035	<u>133,337</u> 91,035	<u>127,059</u> 91,035	<u>112,121</u> 91,035	

A Bound on Knot Probability

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Theorem (with Shonkwiler)

At least 1/2 of equilateral hexagons are unknotted.

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Proof.

Consider the triangulation of the hexagon given by joining vertices 1, 3, and 5 by diagonals and the corresponding action-angle coordinates.

Using a result of Calvo, in either this triangulation or the 2-4-6 triangulation, dihedral angles $\theta_1, \theta_2, \theta_3$ of a hexagonal trefoil must all be either between 0 and π or between π and 2π . Therefore, the fraction of knots is no bigger than

$$2\frac{\text{Vol}([0,\pi]^3) + \text{Vol}([\pi,2\pi]^3)}{\text{Vol}(\mathcal{T}^3)} = \frac{2\pi^3}{8\pi^3} = \frac{1}{2}$$

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A Markov Chain for Convex Polytopes

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To repeat myself:

Action-angle coordinates reduce sampling equilateral polygon space to the (solved) problem of sampling a convex polytope.

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To repeat myself:

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Definition (Hit-and-run Sampling Markov Chain) Given $\vec{p}_k \in \mathcal{P} \subset \mathbb{R}^n$,

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Given $\vec{p}_k \in \mathcal{P} \subset \mathbb{R}^n$,

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Given $\vec{p}_k \in \mathcal{P} \subset \mathbb{R}^n$,

1 Choose a random direction \vec{v} uniformly on S^{n-1} .

2 Let ℓ be the line through \vec{p}_k in direction \vec{v} .

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Given $\vec{p}_k \in \mathcal{P} \subset \mathbb{R}^n$,

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- **3** Choose \vec{p}_{k+1} uniformly on $\ell \cap \mathcal{P}$.

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Theorem (Smith, 1984)

The *m*-step transition probability of hit-and-run starting at any point \vec{p} in the interior of \mathcal{P} converges geometrically to Lesbegue measure on \mathcal{P} as $m \to \infty$.

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Definition (TSMCMC(β))

Given a triangulation *T* of the *n*-gon and associated polytope \mathcal{P} . If $x_k = (\vec{p}_k, \vec{\theta}_k) \in \mathcal{P} \times T^{n-3}$, define x_{k+1} by

- Update \vec{p}_k by a hit-and-run step on \mathcal{P} with probability β .
- Replace θ_k with a new uniformly sampled point in *Tⁿ⁻³* with probability 1 − β.

At each step, construct the corresponding polygon $\alpha(x_k)$ using action-angle coordinates.

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- Replace $\vec{\theta}_k$ with a new uniformly sampled point in T^{n-3} with probability 1β .

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Proposition (with Shonkwiler)

Starting at any polygon, the m-step transition probability of $TSMCMC(\beta)$ converges geometrically to the standard probability measure on Pol(n)/SO(3).

Error Analysis for Integration with TSMCMC(β)

Suppose *f* is a function on polygons. If a run *R* of TSMCMC(β) produces x_1, \ldots, x_m , let

SampleMean(
$$f$$
; R , m) := $\frac{1}{m} \sum_{k=1}^{m} f(\alpha(x_k))$

be the sample average of the values of *f* over the run.

Because TSMCMC(β) converges geometrically, we have

¹ w denotes weak convergence, E(f) is the expectation of $f \in \mathbb{R}^{+}$ and $f \in \mathbb{R}^{+}$

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Theorem (Markov Chain Central Limit Theorem) If *f* is square-integrable, there exists a real number $\sigma(f)$ so that¹

 $\sqrt{m}(\text{SampleMean}(f; R, m) - E(f)) \xrightarrow{w} \mathcal{N}(0, \sigma(f)^2),$

the Gaussian with mean 0 and standard deviation $\sigma(f)^2$.

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$\mathsf{TSMCMC}(\beta)$ Error Bars

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Given a length-*m* run *R* of TSMCMC and a square integrable function $f: M \to \mathbb{R}$, we can compute SampleMean(f; R, m), there is a statistically consistent estimator called the **Geyer IPS Estimator** $\bar{\sigma}_m(f)$ for $\sigma(f)$.

According to the estimator, a 95% confidence interval for the expectation of f is given by

 $E(f) \in \text{SampleMean}(f; R, m) \pm 1.96\bar{\sigma}_m(f)/\sqrt{m}.$

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Experimental Observation

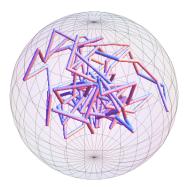
With 95% confidence, we can say that the fraction of knotted equilateral hexagons is between 1.1 and 1.5 in 10,000.

Confined Polygons

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Definition

A polygon $p \in Pol(n; \vec{r})$ is in *rooted spherical confinement* of radius *r* if each diagonal length $d_i \leq r$. Such a polygon is contained in a sphere of radius *r* centered at the first vertex.



Proposition (with Shonkwiler)

Polygons in rooted spherical confinement of radius r have action-angle coordinates given by the polytope

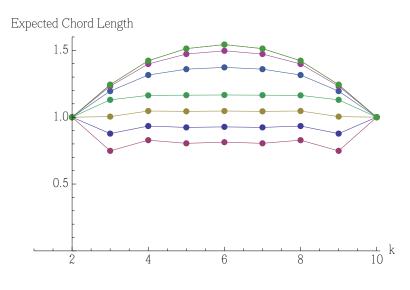
$$0 \le d_1 \le 2$$
 $1 \le d_i + d_{i+1} \ |d_i - d_{i+1}| \le 1$ $0 \le d_{n-3} \le 2$

with the additional linear inequalities

$$d_i \leq r$$
.

These polytopes are simply subpolytopes of the fan triangulation polytopes. Many other confinement models are possible!

Expected Chordlength Theorem for Confined 10-gons



Confinement radii are 1.25, 1.5, 1.75, 2, 3, 4, and 5.

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Thank you!

Thank you for listening!



References

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