

The First Fundamental Form, lengths, angles, and areas.

We finished last class with a description of a quadratic form as an inner product determined by a symmetric matrix A :

$$Q_A(\vec{v}, \vec{w}) = \langle \vec{v}, A\vec{w} \rangle$$

Here is one use of a quadratic form.

Given ~~a~~ vectors $\vec{v} = v_1 \vec{b}_1 + \dots + v_n \vec{b}_n$
 $\vec{w} = w_1 \vec{b}_1 + \dots + w_n \vec{b}_n$

written in terms of an arbitrary basis $\vec{b}_1, \vec{b}_2, \dots, \vec{b}_n$ for ~~\mathbb{R}^n~~ , how can we compute $\vec{v} \cdot \vec{w}$?
 } a subspace \mathbb{R}^n of \mathbb{R}^k

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By linearity,

$$\vec{v} \cdot \vec{w} = \sum_{i,j=1}^n v_i w_j (\vec{b}_i \cdot \vec{b}_j)$$

or, if A is the matrix

$$\begin{bmatrix} \vec{b}_1 \cdot \vec{b}_1 & \dots & \vec{b}_1 \cdot \vec{b}_n \\ \vdots & \ddots & \vdots \\ \vec{b}_n \cdot \vec{b}_1 & \dots & \vec{b}_n \cdot \vec{b}_n \end{bmatrix}$$

then

$$\begin{aligned} \vec{v} \cdot \vec{w} &= \cancel{\sum_{i,j=1}^n v_i w_j A_{ij}} \\ &= \sum_{i=1}^n v_i \sum_{j=1}^n A_{ij} w_j \\ &= \langle \vec{v}, A\vec{w} \rangle \end{aligned}$$

This is the geometric interpretation of the matrix A :

A_{ij} = the inner product of e_i and e_j according to the Q_A inner product

~~On a parame~~

Example. $A = \begin{bmatrix} 1 & 2 \\ 2 & 5 \end{bmatrix}$. $\vec{v} = (1, 2)$, $\vec{w} = (1, 1)$.

$$Q_A(\vec{v}, \vec{w}) = (1, 2) \cdot A \begin{bmatrix} 1 \\ 1 \end{bmatrix} \\ = (1, 2) \cdot (3, 7) = 17.$$

If $\vec{X}: U \subset \mathbb{R}^2 \rightarrow \mathbb{R}^3$ is a parametrized surface, at any point ~~(u, v)~~ $(u_0, v_0) = p_0$ on the u - v plane we have the quadratic form determined by

$$A_{p_0} = \begin{bmatrix} \vec{X}_u \cdot \vec{X}_u & \vec{X}_u \cdot \vec{X}_v \\ \vec{X}_v \cdot \vec{X}_u & \vec{X}_v \cdot \vec{X}_v \end{bmatrix}$$

We usually call this matrix

$$A_{p_0} = \begin{bmatrix} E & F \\ F & G \end{bmatrix}$$

Definition. The first fundamental form of X at $p = (u_0, v_0)$ is the inner product

$$I_p(\vec{v}, \vec{w}) \quad \text{or} \quad \langle \vec{v}, \vec{w} \rangle_p$$

given by the matrix $\begin{bmatrix} E & F \\ F & G \end{bmatrix}$.

Note that \vec{X}_u, \vec{X}_v depend on p , so this matrix changes from point to point.

~~Note~~

Proposition. I_p is positive-definite.

Proof. We know that

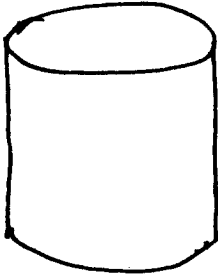
$$I_p(\vec{v}, \vec{v}) = (v_1 \vec{X}_u + v_2 \vec{X}_v) \cdot (v_1 \vec{X}_u + v_2 \vec{X}_v)$$

where \cdot is the dot product in \mathbb{R}^3 by our discussion above. Hence

$$I_p(\vec{v}, \vec{v}) \geq 0, \quad \text{with} \quad \vec{v} = 0 \iff I_p(\vec{v}, \vec{v}) = 0.$$

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Caution! Do Carmo writes $I_p(\vec{v})$ for $I_p(\vec{v}, \vec{v})$.

Example. The cylinder  has the parametrization

$$\vec{X}(u, v) = (\cos u, \sin u, v).$$

We see that

$$\vec{X}_u = (-\sin u, \cos u, 0)$$

$$\vec{X}_v = (0, 0, 1)$$

so

$$E = \vec{X}_u \cdot \vec{X}_u = 1, \quad F = \vec{X}_u \cdot \vec{X}_v = 0.$$

$$G = \vec{X}_v \cdot \vec{X}_v = 1.$$

Example. The xy plane is parametrized by $\vec{X}(u,v) = (u, v, 0)$. We see that

$$\vec{X}_u = (1, 0, 0) \quad \vec{X}_v = (0, 1, 0)$$

and

$$E = 1 \quad F = 0 \quad G = 1.$$

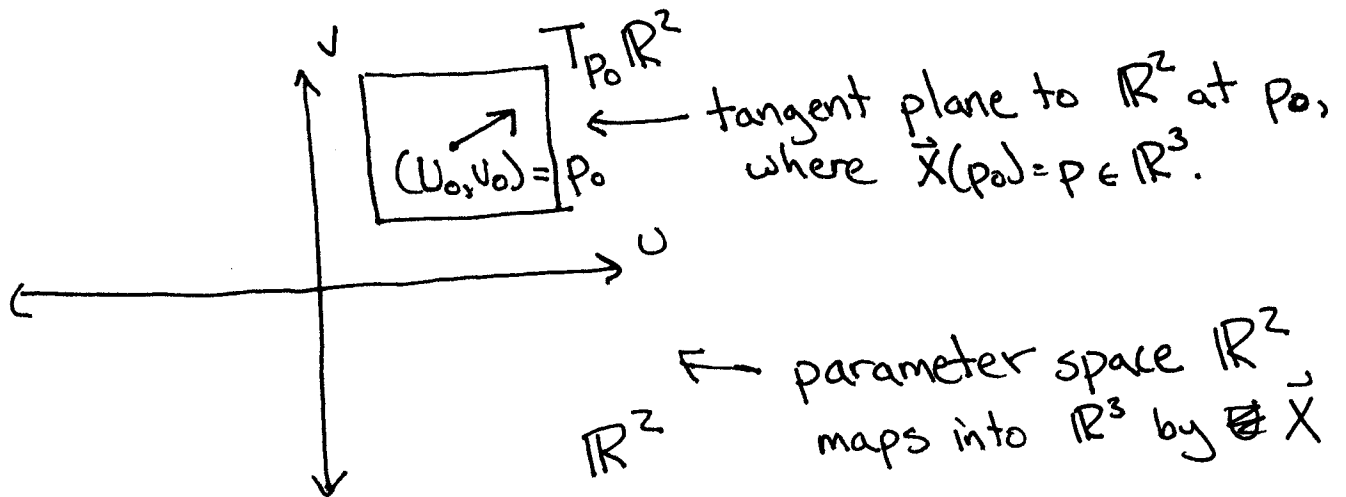
The same result as the cylinder!

(This is not a coincidence...)

Computing with I_p

but subtle

We now make an important[^] distinction



The tangent plane $T_{p_0} \mathbb{R}^2$ to the u - v plane is a vector space with inner product I_p . We can measure length by I_p , as $\|\vec{v}\|_p = \sqrt{I_p(\vec{v}, \vec{v})}$.

The u - v plane does not have a useful inner product. We must measure length by integration.

Let $\alpha(t): \overset{[0, l]}{\mathbb{R}} \rightarrow \mathbb{R}^2$, $\alpha(t) = (u(t), v(t))$ be a parametrized curve on our surface.

Then

$$\text{Length}(\alpha) = \int_0^l \sqrt{I_p(\alpha'(t), \alpha'(t))} dt.$$

$$= \int_0^l \sqrt{E(u')^2 + 2F u'v' + G(v')^2} dt$$

This is sometimes written

$$" ds^2 = E du^2 + 2F du dv + G dv^2. "$$

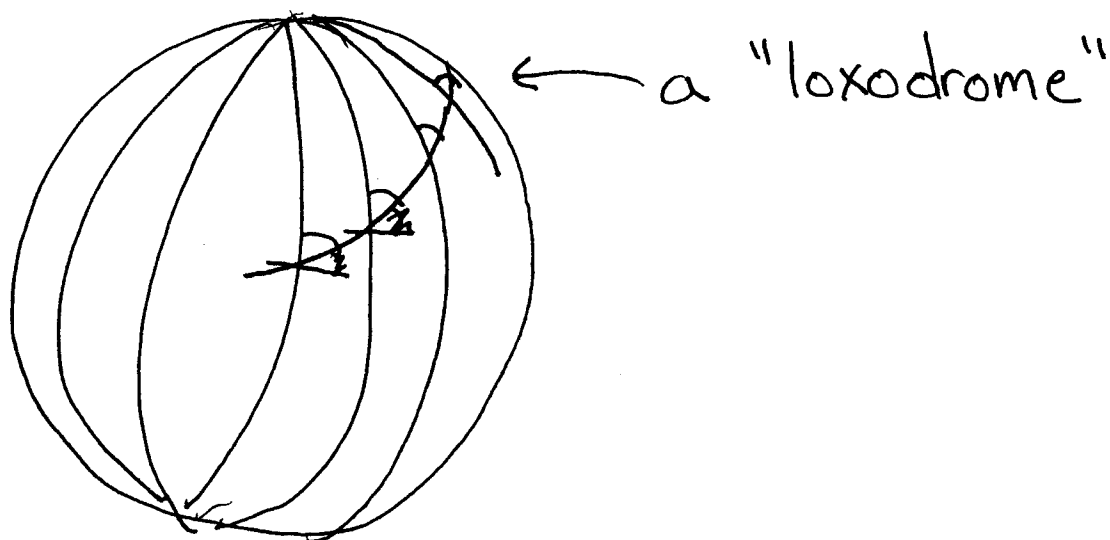
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We can also ^{define} ~~measure~~ the angle Θ between vectors \vec{v} and \vec{w} in $T_p \mathbb{R}^2$ by

$$\cos \Theta = \frac{I_p(\vec{v}, \vec{w})}{\sqrt{I_p(\vec{v}, \vec{v}) I_p(\vec{w}, \vec{w})}}$$

In particular, X_u and X_v are orthogonal $\Leftrightarrow F = I_p\left(\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, (0, 1)\right) = 0$.

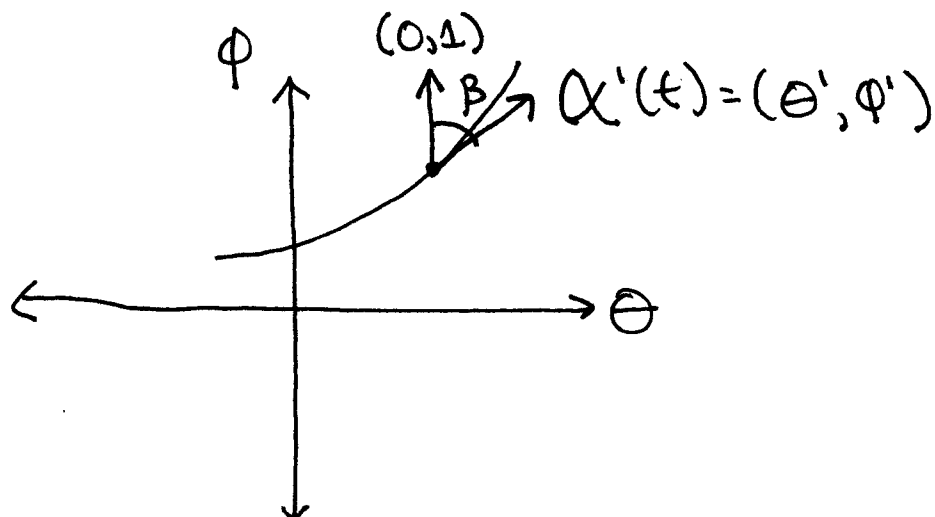
Example. Let $X(\theta, \varphi) = (\sin \varphi \cos \theta, \sin \varphi \sin \theta, \cos \varphi)$ parametrize the sphere. Find the equation of a curve in the (θ, φ) plane which makes a constant angle with the curves $\theta = \text{constant}$.



We compute

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$$E = \sin^2 \varphi \quad F = 0 \quad G = 1$$



Observe that

$$\begin{aligned} \cos \beta &= \frac{I_p((\theta', \varphi'), (0, 1))}{\|(0, 1)\|_p \|\alpha'(t)\|_p} \\ &= \frac{\varphi'}{1 \sqrt{\sin^2 \varphi (\theta')^2 + (\varphi')^2}} \end{aligned}$$

So we have

$$(\cos^2 \beta) (\sin^2 \varphi (\theta')^2 + (\varphi')^2) = (\varphi')^2$$

$$\cos^2 \beta (\theta')^2 = \frac{(\varphi')^2 (1 - \cos^2 \beta)}{\sin^2 \varphi}$$

or

$$\frac{\Theta'}{\tan \beta} = \pm \frac{\Phi'}{\sin \Phi}$$

Integrating both sides with respect to t ,
we get

$$\frac{\Theta}{\tan \beta} + C = \pm \ln \tan \left(\frac{\Phi}{2} \right).$$

or

$$\Theta = \pm \tan \beta \left(\ln \tan \left(\frac{\Phi}{2} \right) \right) + C$$

where C is determined by the starting point. The integration comes from the half-angle formula

$$\sin \Phi = \sin 2 \left(\frac{\Phi}{2} \right) = 2 \sin \Phi/2 \cos \Phi/2$$

so

$$\int \frac{\Phi'(t) dt}{2 \sin \Phi/2 \cos \Phi/2} = \int \frac{1}{\sin x \cos x} dx = \int \frac{\cos x}{\sin x} \cdot \frac{1}{\cos^2 x} dx$$

$\swarrow x = \Phi/2 \quad \nearrow$

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$$= \int \frac{1}{\tan x} \cdot \frac{1}{\cos^2 x} dx$$

$$= \ln(\tan x) = \ln \tan \frac{\phi}{2}.$$

We last consider area on surfaces.

In \mathbb{R}^3 , the area spanned by \vec{v} and \vec{w} is given by $|\vec{v} \times \vec{w}|$. We use this to define

Definition. If $R \subset U$ is a ~~closed~~ bounded region in the parameter plane of a surface given by $\vec{X}: U \subset \mathbb{R}^2 \rightarrow \mathbb{R}^3$, then

$$\text{Area}(R) = \iint_R |\vec{X}_u \times \vec{X}_v| du dv$$

We can use the handy identity

$$|\vec{X}_u \times \vec{X}_v|^2 + (\vec{X}_u \cdot \vec{X}_v)^2 = |\vec{X}_u|^2 |\vec{X}_v|^2$$

to write

$$\text{Area}(R) = \iint_R \sqrt{EG - F^2} \, du \, dv$$

where we call $\sqrt{EG - F^2}$ the "element of area".

(This quantity is the determinant of the matrix $\begin{bmatrix} E & F \\ F & G \end{bmatrix}$ which maps $T_{p_0} \mathbb{R}^2 \rightarrow T_p S$.)

Example. The area of a sphere.