

# Computations with $K$ and $H$

We have now learned that

$$K = \frac{eg - f^2}{EG - F^2} \quad \text{and} \quad H = \frac{(eG + gE) - 2fF}{2(EG - F^2)},$$

and given nice formulae for the  $E, F, G$  and  $e, f, g$ :

$$E = \langle x_u, x_u \rangle$$

$$F = \langle x_u, x_v \rangle$$

$$G = \langle x_v, x_v \rangle$$

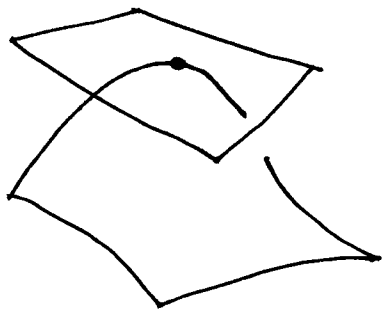
$$e = \langle x_u, N_u \rangle$$

$$f = \langle x_u, N_v \rangle$$

$$g = \langle x_v, N_v \rangle$$

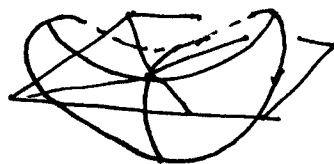
We want to see how to draw some geometric information from these.

Observation.



$T_p S$  lies on  
one side of  $S$

elliptic



$T_p S$  cuts  $S$

hyperbolic

Let's view  $\mathbb{I}_p$  in a new light.

When we defined  $\mathbb{I}_p$ , we proved that the matrix  $\begin{bmatrix} E & F \\ F & G \end{bmatrix}$  and the form  $\mathbb{I}_p$  were "positive-definite", meaning that

$$\mathbb{I}_p(\vec{v}) \geq 0, \quad \mathbb{I}_p(\vec{v}) = 0 \Leftrightarrow \vec{v} = \vec{0}.$$

We recall

$M$  is positive definite  $\Leftrightarrow$  all  $M$ 's eigenvalues are  $> 0$ .

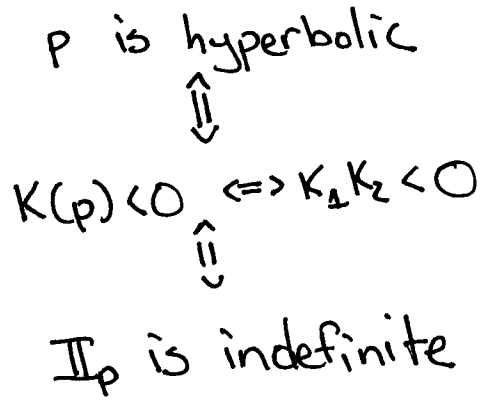
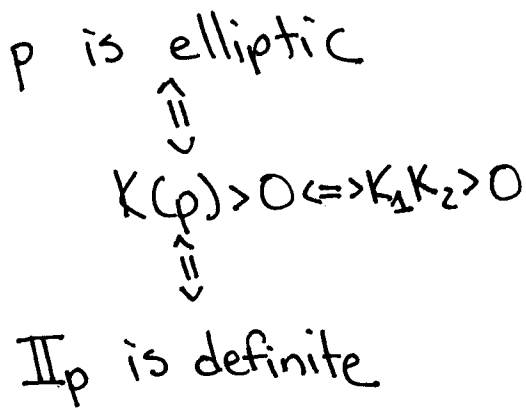
A form is negative definite if

$$Q(\vec{v}) \leq 0, \quad Q(\vec{v}) = 0 \Leftrightarrow \vec{v} = \vec{0}$$

and it is definite if positive or negative definite. A form is indefinite if

$$Q(\vec{v}) < 0, \quad Q(\vec{w}) > 0 \quad \text{for some } \vec{v}, \vec{w}.$$

We can then give a new interpretation for curvature



at parabolic points,  $\mathbb{I}_p$  turns out to be semi definite, meaning

$$\textcircled{\otimes} \mathbb{I}_p(\vec{v}) \geq 0 \text{ for all } \vec{v} \neq 0$$

or

$$\mathbb{I}_p(\vec{v}) \leq 0 \text{ for all } \vec{v} \neq 0$$

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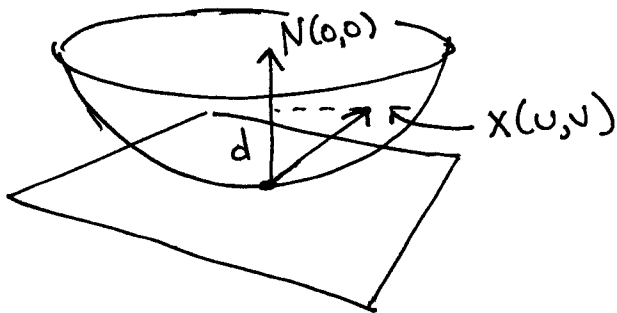
Proposition. If  $p \in S$  is an elliptic point,  $\exists$  some neighborhood  $V$  of  $p$  in  $S$  so that all points in  $V$  belong to the same side of  $T_p S$ .

If  $p \in S$  is a hyperbolic point; then any neighborhood  $V$  of  $p$  contains points on both sides of  $T_p S$ .

Proof. Suppose that  $p = x(0,0) = (0,0,0)$ . Then

$$x(u,v) = x_u u + x_v v + \frac{1}{2} (x_{uu} u^2 + 2x_{uv} uv + x_{vv} v^2) + R(u,v)$$

where  $\lim_{(u,v) \rightarrow 0} \frac{R(u,v)}{|(u,v)|^2} \rightarrow 0$ , by Taylor's Theorem.



The height of  $x(u,v)$  over the tangent plane is given by

$$\begin{aligned} d &= \langle x, N \rangle \\ &= \langle x_u, N \rangle u + \langle x_v, N \rangle v + \frac{1}{2} \left( \langle x_{uu}, N \rangle u^2 + 2 \langle x_{uv}, N \rangle uv + \langle x_{vv}, N \rangle v^2 \right) \\ &\quad + \langle R, N \rangle. \end{aligned}$$

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$$= \frac{1}{2} (e u^2 + 2f uv + g v^2) + \langle R, N \rangle$$

$$= \frac{1}{2} \Pi_p \left( \begin{bmatrix} u \\ v \end{bmatrix} \right) + \langle R, N \rangle.$$

If  $p$  is an elliptic point, then  $\Pi_p$  is positive or negative definite and  $\frac{1}{2}\Pi_p(\vec{\omega})$  has the same sign for all  $\vec{\omega}$ .

If  $p$  is a hyperbolic point, then  $\Pi_p$  is indefinite and  $\Pi_p(\vec{\omega})$  takes different signs for different vectors.

For small enough  $(u, v)$ , we can ignore  $\langle R, N \rangle$  and these observations prove the result.

Let's go back to

asymptotic directions  $\Leftrightarrow \Pi_p(\vec{v}) = 0$ .

We see that  $\alpha(t) = (u(t), v(t))$  is an asymptotic curve  $\Leftrightarrow$

$$e(u')^2 + 2f(u'v') + g(v')^2 \equiv 0.$$

This is a particular differential equation for  $\alpha'(t)$ .

Example. On the torus of revolution

$$e = r, \quad f = 0, \quad g = \cos u (a + r \cos u)$$

so  $\alpha(t)$  is an asymptotic curve  $\Leftrightarrow$

$$r(u')^2 + \cos u (a + r \cos u)(v')^2 = 0$$

or

$$\frac{d}{dv} u(v) = \frac{u'}{v'} = -\frac{\cos u}{r} (a + r \cos u)$$

$\approx \neq$

We could solve this differential equation for  $u(v)$ .

(Can it be solved when  $\cos u > 0$ ?)

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What about principal directions?

Recall that  $\alpha(t)$  is a line of curvature

$$\Leftrightarrow dN_p(\alpha'(t)) = \lambda(t) \alpha'(t).$$

or if  $\alpha'(t) = (u'(t), v'(t))$ , then

$$a_{11} u' + a_{12} v' = \lambda u' \quad (1)$$

$$a_{21} u' + a_{22} v' = \lambda v' \quad (2)$$

Multiplying (1) by  $v'$  and (2) by  $u'$ ,  
and subtracting them, we get

$$-a_{21} (v')^2 + (a_{12} - a_{22}) v' u' + a_{12} (u')^2 = 0$$

or (using the Weingarten equations)

$$(fE - eF)(u')^2 + (gE - eG) u' v' + (gF - fG)(v')^2 = 0$$

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Example. On the torus of revolution,

$$E = r^2 \quad F = 0 \quad G = (a + r \cos u)^2$$

so we have

$$[r^2 \cos u (a + r \cos u) - r (a + r \cos u)^2] u' v' = 0$$

or

$$r (a + r \cos u) [r \overset{\cos u}{\cancel{r}} - a \mp r \cos u] u' v' = 0$$

or

$$-r (a + r \cos u) [a + \cancel{r \cos u}] u' v' = 0$$

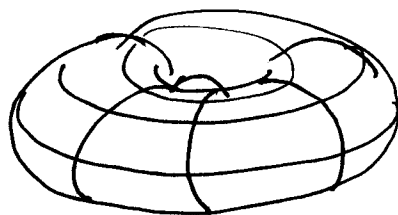
~~This tells us that  $u' = 0$ ,  $v' = 0$  or~~

$$\cancel{a + r \cos u = r}$$

$\Rightarrow$

$$\cancel{\cos u = \frac{a}{r}, \text{ which is impossible, since } a > r.}$$

This tells us that  $u' = 0$  or  $v' = 0$  and the lines of curvature are





Notice that what we really needed here was the observation that

$$F = f = 0.$$

In fact,

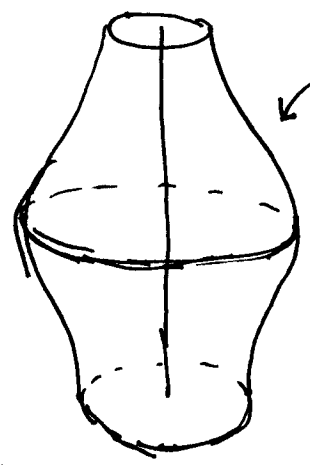
Coordinate curves are lines of curvature



$$F = f = 0$$

Some other special cases are instructive.

Surfaces of Revolution.



$$(\varphi(v), \psi(v)) = \alpha(v)$$

$$X(u, v) = (\varphi(v) \cos u, \varphi(v) \sin u, \psi(v)).$$

Working out the coefficients  $E, F, G, e, f, g$  we compute

$$X_u = (-\varphi(v) \sin u, \varphi(v) \cos u, 0)$$

$$X_v = (\varphi'(v) \cos u, \varphi'(v) \sin u, \psi'(v))$$

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$$X_{uu} = (-\varphi(v) \cos u, -\varphi(v) \sin u, 0)$$

$$X_{uv} = (-\varphi'(v) \sin u, \varphi'(v) \cos u, 0)$$

$$X_{vv} = (\varphi''(v) \cos u, \varphi''(v) \sin u, \psi''(v)).$$

So

$$E = \varphi^2(v). \quad F = 0. \quad G = (\varphi')^2 + (\psi')^2 = |\alpha'(v)|^2.$$

We usually assume that  $\alpha(v)$  is parametrized by arclength, so  $G = 1$ . Thus

$$\sqrt{EG - F^2} = \varphi$$

and we have

$$e = \frac{1}{\varphi} \begin{vmatrix} X_u & X_v & X_{uu} \end{vmatrix} = \frac{1}{\varphi} \begin{vmatrix} -\varphi \sin u & \varphi' \cos u & -\varphi \cos u \\ \varphi \cos u & \varphi' \sin u & -\varphi \sin u \\ 0 & \psi' & 0 \end{vmatrix}$$

$$= \frac{1}{\varphi} (-\psi' (\varphi^2 \sin^2 u - (-\varphi^2 \cos^2 u)))$$

$$= -\varphi \psi'$$

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$$f = \frac{1}{\varphi} (x_u, x_v, x_{uv}) = \frac{1}{\varphi} \begin{vmatrix} -\varphi \sin u & \varphi' \cos u & -\varphi' \sin u \\ \varphi \cos u & \varphi' \sin u & \varphi' \cos u \\ 0 & \psi' & 0 \end{vmatrix}$$

$$= \frac{1}{\varphi} \left( -\psi' (-\varphi \varphi' \sin u \cos u - (-\varphi \varphi' \sin u \cos u)) \right)$$

$$= 0.$$

$$g = \frac{1}{\varphi} (x_u, x_v, x_{uv}) = \frac{1}{\varphi} \begin{vmatrix} -\varphi \sin u & \varphi' \cos u & \varphi'' \cos u \\ \varphi \cos u & \varphi' \sin u & \varphi'' \sin u \\ 0 & \psi' & \psi'' \end{vmatrix}$$

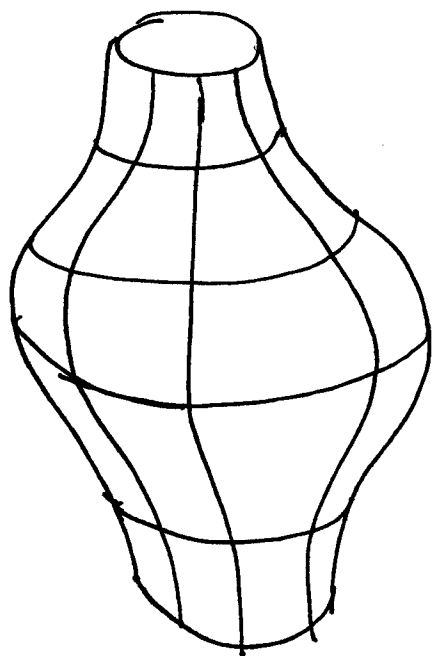
$$= \frac{1}{\varphi} \left( -\psi' (-\varphi \varphi'' \sin^2 u - \varphi \varphi'' \cos^2 u) + \psi'' (-\varphi \varphi' \sin^2 u - \varphi \varphi' \cos^2 u) \right)$$

$$= \psi' \varphi'' - \psi'' \varphi'.$$

Notice that  $g$  should look familiar! From your old homework, the curvature of  $\alpha(v) = (\varphi(v), \psi(v))$

$$K(v) = \frac{|\varphi' \psi'' - \varphi'' \psi'|}{((\varphi')^2 + (\psi')^2)^{3/2}} = \frac{|\varphi' \psi'' - \varphi'' \psi'|}{\text{since } (\varphi, \psi) \text{ is unit speed.}}$$

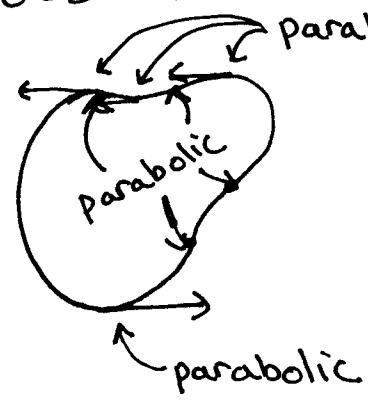
We know that the coordinate curves are lines of curvature here, too:



$$K = \frac{eg - f^2}{EG - F^2} = \frac{-\phi\psi'(\psi'\phi'' - \psi''\phi')}{\phi^2}$$

$$= -\frac{1}{\phi} \psi'(\psi'\phi'' - \psi''\phi')$$

So where does  $K$  vanish? (Parabolic points?)



$$\psi' = 0$$

or

$$\psi'\phi'' - \psi''\phi' = 0$$

(the curve  $\alpha$  has a point of zero curvature)

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We can come up with a better expression for  $K$ . Notice that

$$\phi'^2 + \psi'^2 = 1,$$

so differentiating w.r.t.  $v$ , we get

$$2\phi'\phi'' + 2\psi'\psi'' = 0, \text{ or } \phi'\phi'' = -\psi'\psi''$$

Thus

$$K = \frac{-(\psi')^2 \phi'' + \psi' \psi'' \phi'}{\phi} = \frac{-(\psi')^2 - (\phi')^2}{\phi} \phi'' = -\frac{\phi''}{\phi}.$$

Application.

We then know that a surface of revolution has constant Gaussian curvature  $K_0$  if (and only if)

$$-\frac{\phi''}{\phi} = K_0, \text{ or } \phi'' = -K_0 \phi$$

What are the solutions of this O.D.E.?

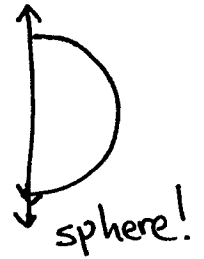
$$K_0 = +1$$

$$\varphi'' = -\varphi$$

$$\varphi(v) = \sin v$$

or  
cos v

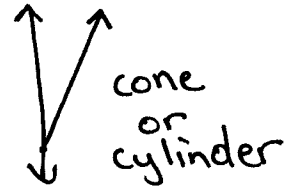
$$\psi(v) = \cos v \text{ or } \sin v$$



$$K_0 = 0$$

$$\varphi'' = 0$$

$$\varphi(v) = av + b$$



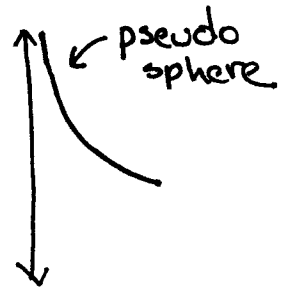
$$K_0 = -1$$

$$\varphi'' = \varphi$$

$$\varphi(v) = \cosh v$$

or  
sinh v

$$\psi(v) = \int \sqrt{1 - \sinh^2 v} dv$$

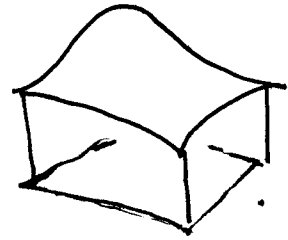


It will be a homework exercise to work out a better parametrization for this surface!

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Example. Surfaces which are graphs of functions  $h(u,v)$ .

$$X(u,v) = (u, v, h(u,v))$$



So

$$X_u = (1, 0, h_u)$$

$$X_v = (0, 1, h_v)$$

$$X_{uu} = (0, 0, h_{uu})$$

$$X_{uv} = (0, 0, h_{uv})$$

$$X_{vv} = (0, 0, h_{vv})$$

Here

$$E = 1 + (h_u)^2 \quad F = h_u h_v \quad G = 1 + (h_v)^2$$

then

$$\begin{aligned} EG - F^2 &= (1 + (h_u)^2)(1 + (h_v)^2) - (h_u^2)(h_v^2) \\ &= 1 + (h_u)^2 + (h_v)^2 \end{aligned}$$

so

$$(X_u, X_v, X_{uv}) = \begin{vmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ h_u & h_v & h_{uv} \end{vmatrix} = h_{uv}$$

$$(X_u, X_u, X_{uv}) = \begin{vmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ h_u & h_v & h_{uv} \end{vmatrix} = h_{uv}$$

$$(X_u, X_v, X_{uv}) = \begin{vmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ h_u & h_v & h_{uv} \end{vmatrix} = h_{uv}$$

and

$$e = \frac{h_{uv}}{(1 + h_u^2 + h_v^2)^{1/2}}$$

$$f = \frac{h_{uv}}{(1 + h_u^2 + h_v^2)^{1/2}}$$

$$g = \frac{h_{uv}}{(1 + h_u^2 + h_v^2)^{1/2}}$$



This means that

$$K = \frac{eg - f^2}{EG - F^2} = \frac{h_{uu}h_{vv} - h_{uv}^2}{(1 + h_u^2 + h_v^2)^2}.$$

In particular, we see that the sign of  $K$  is given by the determinant of the Hessian matrix

$$H = \begin{bmatrix} h_{uu} & h_{uv} \\ h_{uv} & h_{vv} \end{bmatrix},$$

telling us that the Hessian and the second fundamental form are related!

In fact given any direction  $\vec{v}$ , the second derivative of  $h$  in that direction is given by

$$\langle H\vec{v}, \vec{v} \rangle = \left. \frac{d^2}{d\epsilon^2} h(\vec{x} + \epsilon\vec{v}) \right|_{\epsilon=0}$$