

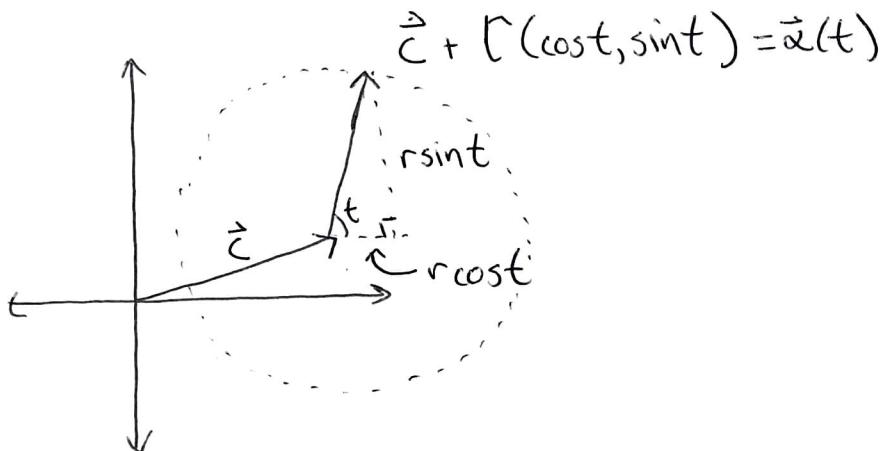
Parametrized curves, examples and constructions

Recall that a parametrized curve is a map $\vec{\alpha}: \mathbb{R} \rightarrow \mathbb{R}^n$. We will now study some example curves.

Example. The circle of radius r with center $\vec{c} = (c_1, c_2)$ in \mathbb{R}^2 is described implicitly by

$$(x - c_1)^2 + (y - c_2)^2 = r^2$$

We can parametrize this curve by



(2)

Notice that

$$\vec{\alpha}(t) = (c_1 + r\cos t, c_2 + r\sin t)$$

obeys

$$\begin{aligned} (\alpha_1(t) - c_1)^2 + (\alpha_2(t) - c_2)^2 &= \\ &= (r \cos t)^2 + (r \sin t)^2 \\ &= r^2 (\cos^2 t + \sin^2 t) = r^2, \end{aligned}$$

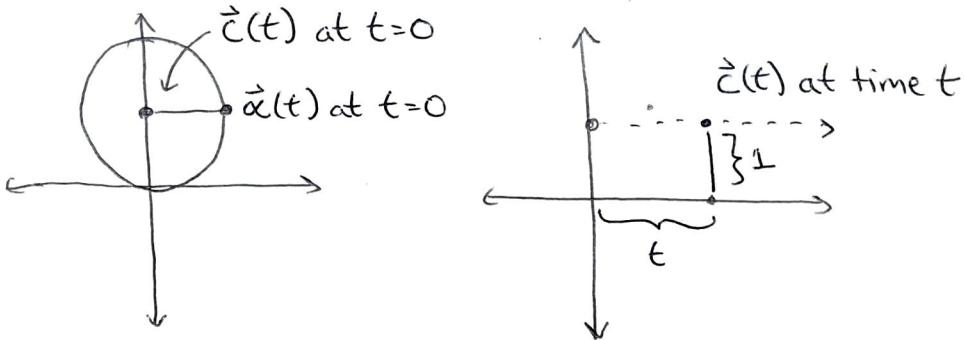
but there is more information in the ~~parametrization~~ parametrization $\vec{\alpha}(t)$ because it tells us when each point on the circle is reached.

Example 2. $\vec{\alpha}(t) = (c_1 + r\cos(t^2), c_2 + r\sin(t^2))$
 also parametrizes the circle of radius r and center $\vec{c} = (c_1, c_2)$.

(3)

We can make some beautiful curves by combining sines and cosines.

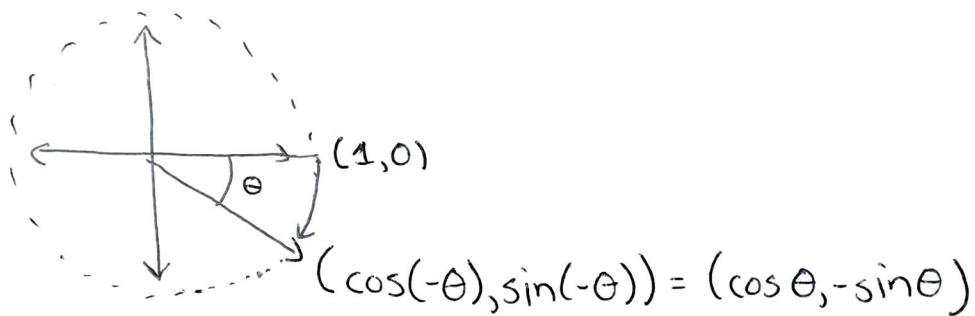
Example. A unit circle starts with center at $(0,1)$ and rolls along the pos. x axis. Parametrize the path of a point starting at $(1,1)$.



If the center of the circle is given by $\vec{c}(t)$, we can assume that the circle is rolling to the right at unit speed, so $\vec{c}(t) = (t, 1)$.

(4)

However, if ~~#~~ a unit circle has rolled t units forward, it has turned by an angle of t radians... in the clockwise direction.



This rotation carries the point at $(1,0)$ ~~to~~ (relative to the center) to the point at $(\cos \theta, -\sin \theta)$ (relative to the center).

Adding these together:

$$\vec{\alpha}(t) = (t + \cos t, 1 - \sin t)$$

(5)

We will work through a more elaborate example of this type of motion in homework when we describe the square-wheeled car.

We often describe curves with a differential equation, so let's remember how to solve (easy) ODEs.

If $u'(t) = F(u(t))$, then

$$\frac{u'(t)}{F(u(t))} = 1$$

$$\int \frac{u'(t)}{F(u(t))} dt = \int 1 dt \quad \begin{array}{l} \text{integrate w.r.t. } t \\ \downarrow \\ du = u'(t) dt \end{array}$$

$$\int \frac{1}{F(u)} du = \int 1 dt$$

so $\int \frac{1}{F(u)} du = t + C$

(6)

If we can do the integral on the left to get some

$$G(u) = \int \frac{1}{F(u)} du$$

then we get an equation

$$G(u) = t$$

which we can try to solve for ~~\Rightarrow~~ $u(t)$.

Example. $u'(t) = u(t)^2$

$$\frac{u'(t)}{u(t)^2} = 1 \Rightarrow \int \frac{1}{u(t)^2} u'(t) dt = \int 1 dt$$

$$\Rightarrow \int \frac{1}{u^2} du = t + C \Rightarrow -\frac{1}{u} = t + C$$

$$\Rightarrow u = -\frac{1}{t+C}$$

$$\text{So } u(t) = -\frac{1}{t+C}, \text{ and indeed } u'(t) = \frac{1}{(t+C)^2} = u(t)^2.$$